Srinath Mahankali

917-771-4679|srinathm@mit.edu

Education

Massachusetts Institute Of Technology

Candidate for Bachelors in Artificial Intelligence and Decision Making; GPA 4.9/5.0

Selected Courses: Advanced Sensorimotor Learning (Graduate), Large Language Models (Graduate), • Computer Vision (Graduate), Statistical Reinforcement Learning (Graduate), Machine Learning (Graduate), Robotics: Science and Systems, Robotic Manipulation, Design and Analysis of Algorithms

Research Experience

Improbable AI Lab, CSAIL, MIT

Undergraduate Researcher | Advisor: Prof. Pulkit Agrawal

- Developing a new algorithm for reinforcement learning agents to explore their environment efficiently and • learn useful skills. Investigated the impact of various intrinsic rewards on exploration. Showed that randomly choosing intrinsic reward functions can lead to better exploration than novelty-based intrinsic rewards.
- Studying the use of a new algorithm, extrinsic-intrinsic policy optimization, for locomotion. Demonstrated that this algorithm improved performance while minimizing energy consumption on a real quadruped.

MIT Mathematics

Undergraduate Researcher | Advisor: Prof. Promit Ghosal

Investigated randomly initialized neural networks (RINNs) experimentally and theoretically. Proved that one-layer RINNs are likely to make near-arbitrary datasets linearly separable. Showed that one-layer RINNs have a higher probability of doing this compared to deeper RINNs on real world, high dimensional datasets.

Simons Institute for the Theory of Computing, UC Berkeley

Undergraduate Researcher | Advisor: Prof. Yunan Yang

- Proved theorems on convergence and stability for the inverse scattering problem for the diffuse wave equation and the Helmholtz equation, depending on the chosen Sobolev norm.
- Conducted research on the convexity of optimal transport-based full-waveform inversion. Proved that choosing the Wasserstein metric rather than the L² norm leads to better convexity in structured settings.

Research Papers

- Mahankali, Srinath, Zhang-Wei Hong, Ayush Sekhari, Alexander Rakhlin, Pulkit Agrawal. Random Latent Exploration for Deep Reinforcement Learning. International Conference on Machine Learning (ICML) 2024.
- Mahankali, Srinath, Chi-Chang Lee, Gabriel B. Margolis, Zhang-Wei Hong, Pulkit Agrawal. Maximizing Quadruped Velocity by Minimizing Energy. International Conference on Robotics and Automation (ICRA) 2024.
- Mahankali, Srinath, Zhang-Wei Hong, Pulkit Agrawal. Does Novelty-Based Exploration Maximize Novelty?
- Ghosal, Promit, Srinath Mahankali, and Yihang Sun. Randomly Initialized One-Layer Neural Networks Make Data Linearly Separable. arXiv preprint arXiv:2205.11716 (2022).
- Mahankali, Srinath, Yunan Yang, Norm-dependent convergence and stability of the inverse scattering series for diffuse and scalar waves. Inverse Problems, 39(5), 054005. (2023)
- Mahankali, Srinath. The convexity of optimal transport-based waveform inversion for certain structured velocity models. SIAM Undergraduate Research Online, 14:109-129 (2021).

Awards & Honors

- 2025 CRA Outstanding Undergraduate Researcher Award Runner Up
- 2024 Goldwater Scholarship Winner
- 2024 Jeremy Gerstle UROP Award in AI
- Paul E. Gray (1954) UROP Endowment Fund Award

January 2020 - August 2022

January 2022 - August 2022

Expected: February 2025

June 2022 - Present

- Regeneron Science Talent Search 2021: Scholar (Top 300) Award
- Mathematical Association of America 2021: Qualified for USAMO

Course Projects

Emergent In-Context Exploration via Partially Observable Random Tasks

Course: 6.S953 Embodied Intelligence

• Proposed a new method for in-context exploration for reinforcement learning agents using linear transformers and partially observable random reward functions. Here is the final project document.

Problem Solving Through Critical Revision

Course: 6.5986 Large Language Models

Studied the use of large language models for solving math word problems. Investigated different prompting strategies including few-shot and chain-of-thought prompting. Here is the final project document.

Reward Function-Conditioned Policies for Exploration

Course: 6.S897 Advanced Sensorimotor Learning

 Proposed a new method for exploration in reinforcement learning and showed improved performance in simple environments compared to state-of-the-art exploration methods. Here is the final project document.

Collision-Free Motion with Goal-Conditioned Reinforcement Learning

Course: 6.4210 Robotic Manipulation

• Studied the use of goal-conditioned reinforcement learning to train policies for robot arms to avoid collisions with obstacles in its environment. Here is the final project document.

Single Image Super-Resolution Using Neural Implicit Representations

Course: 6.869 Computer Vision

• Proposed a new method for single-image super resolution using neural fields. Compared its performance to methods such as bilinear interpolation and deep learning-based methods. Here is the final project document.

Comparing Machine Learning Models for Robust ASL Classification

Course: 6.867 Machine Learning

- Classify images in the ASL alphabet with machine learning methods such as: CNN, PCA/robust PCA with MLP, and PCA/robust PCA with Kernel SVM, comparing their accuracy and robustness to irregular data.
- Here is the final project document.

Leadership and Teaching Experience

Curriculum Designer, Momentum AI

- Designed an AI curriculum for high school students from underrepresented backgrounds, covering Python, NumPy, Keras, basic linear algebra, gradient descent, and neural networks (MLPs, CNNs, RNNs).
- Designed lesson plans that simplified advanced AI concepts and showcased real-world applications, making the material both accessible and engaging to inspire interest in the field.

Captain, New York City Math Team

- Recruited 130+ members, strategized for national competitions, and created curriculum for weekly practice
- Team Awards: 1st Place at Princeton University Mathematics Competition 2020 (held in 2021), 2nd Place at • American Regions Mathematics League 2021, 3rd Place at Harvard-MIT Mathematics Tournament 2021

Teaching Assistant, Stuyvesant Math Team

• Organized virtual lessons for freshmen and senior math team members during the pandemic.

Skills

Software: Python, PyTorch, Robot Operating System (ROS), LaTeX, MATLAB, Java, Typescript, HTML, CSS

June 2023 - August 2023

March 2023 - May 2023

March 2024 - May 2024

September 2020 - June 2021

September 2019 - June 2021

March 2022 - May 2022

October 2021 - December 2021

October 2022 - December 2022

October 2022 - December 2022